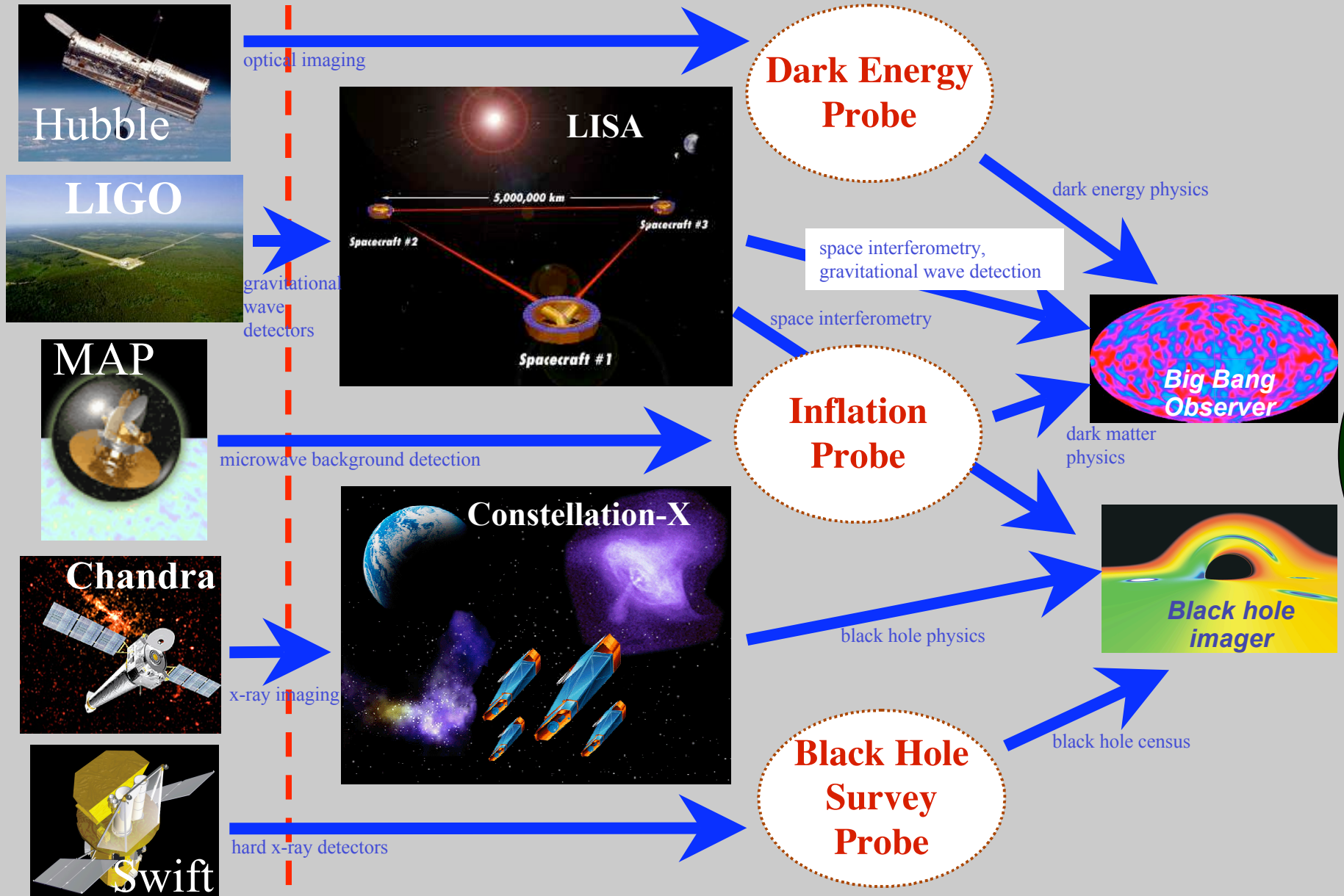


**MAXIM**  
**The Black Hole Imager**

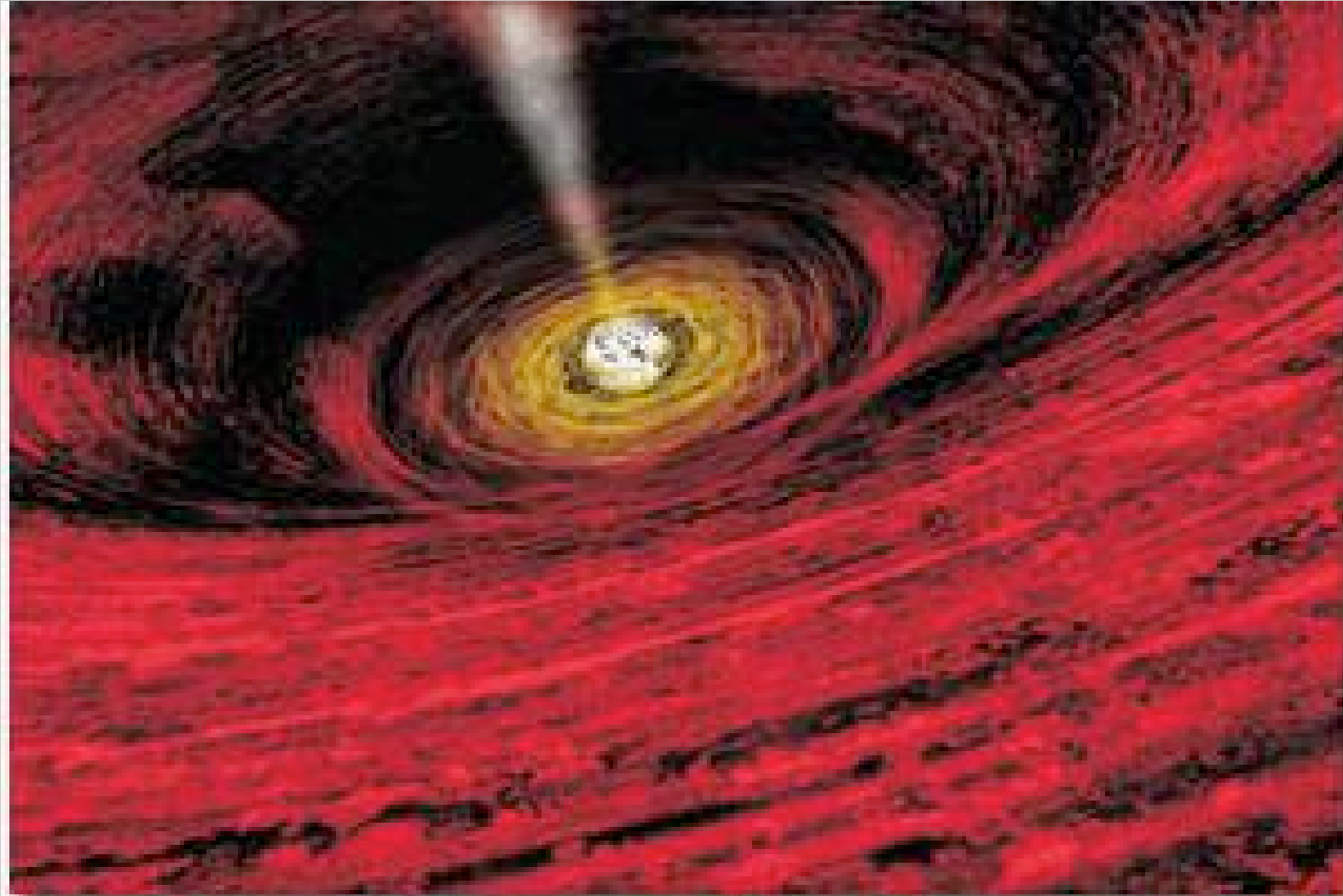
Webster Cash  
Keith Gendreau  
and  
The Maxim Team

# The Beyond Einstein Program



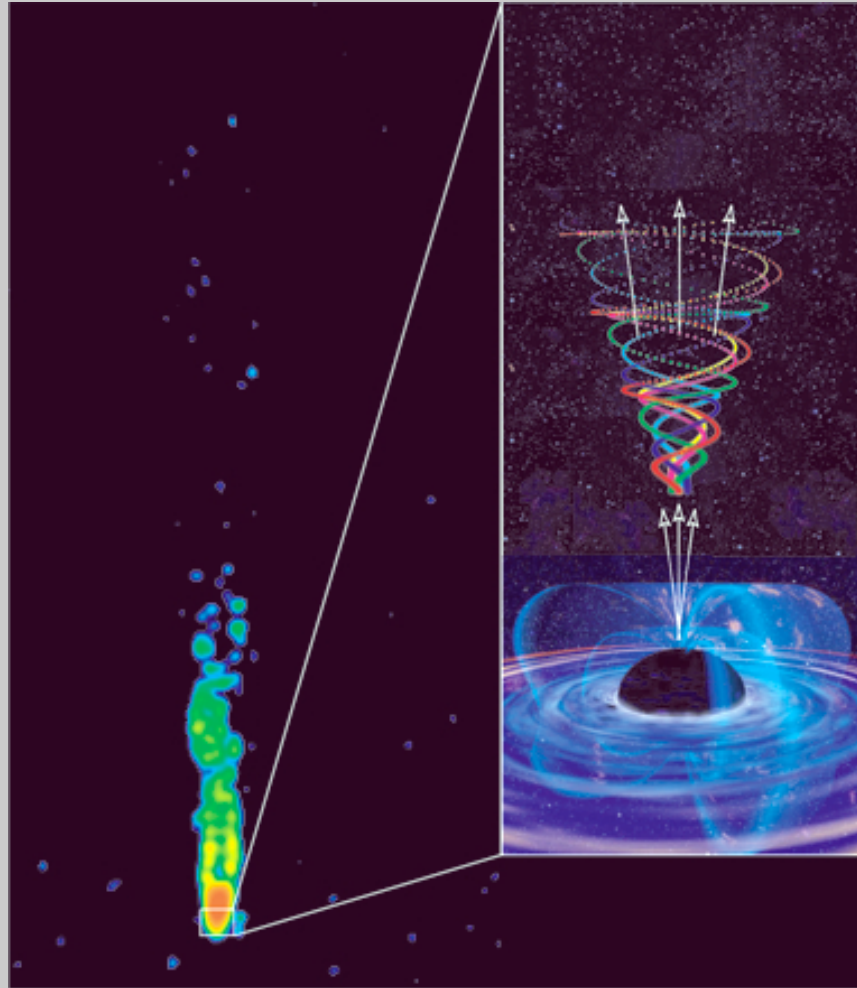
Science and Technology Precursors

## Science Objectives for the Black Hole Imager (1)



**Map the motions of gas in the vicinity of a black hole event horizon and compare to GR predictions**

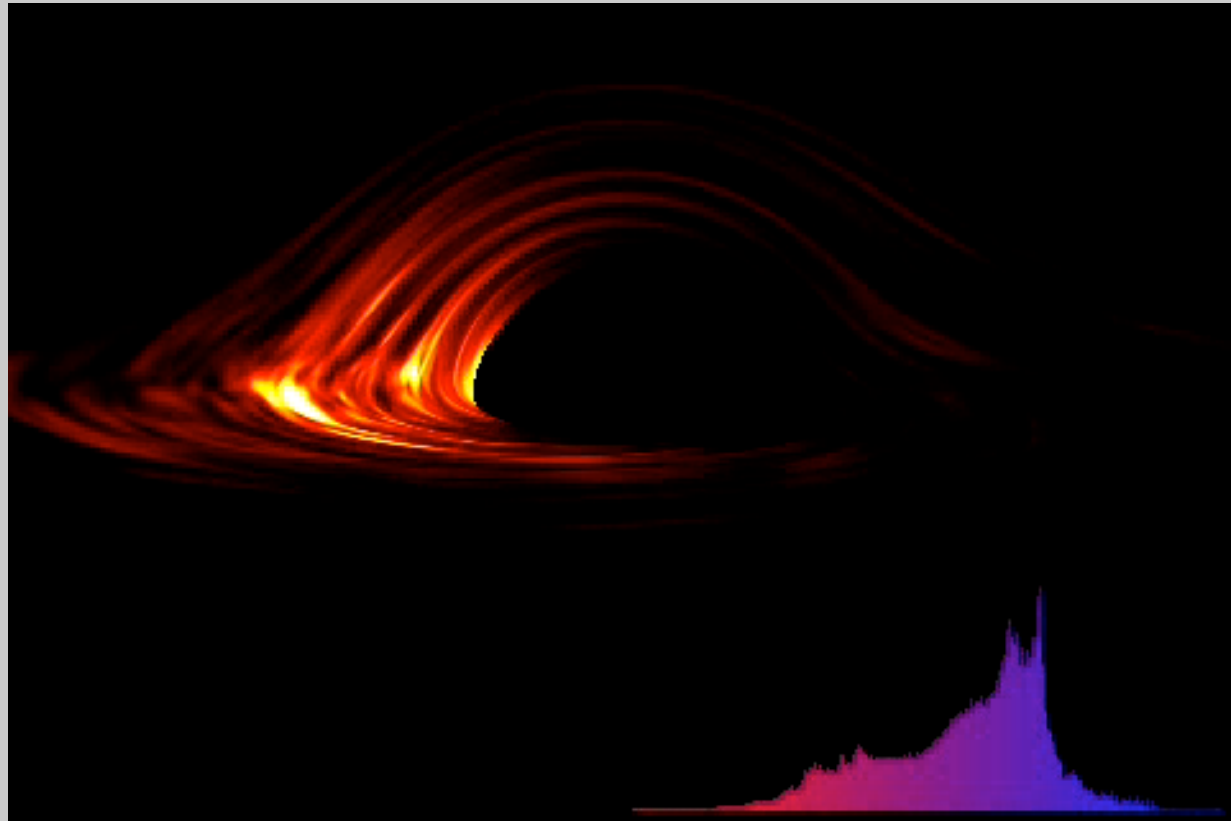
## Science Objectives for the Black Hole Imager (2)



**Determine how relativistic jets are formed as well as the role of black hole spin in the process**



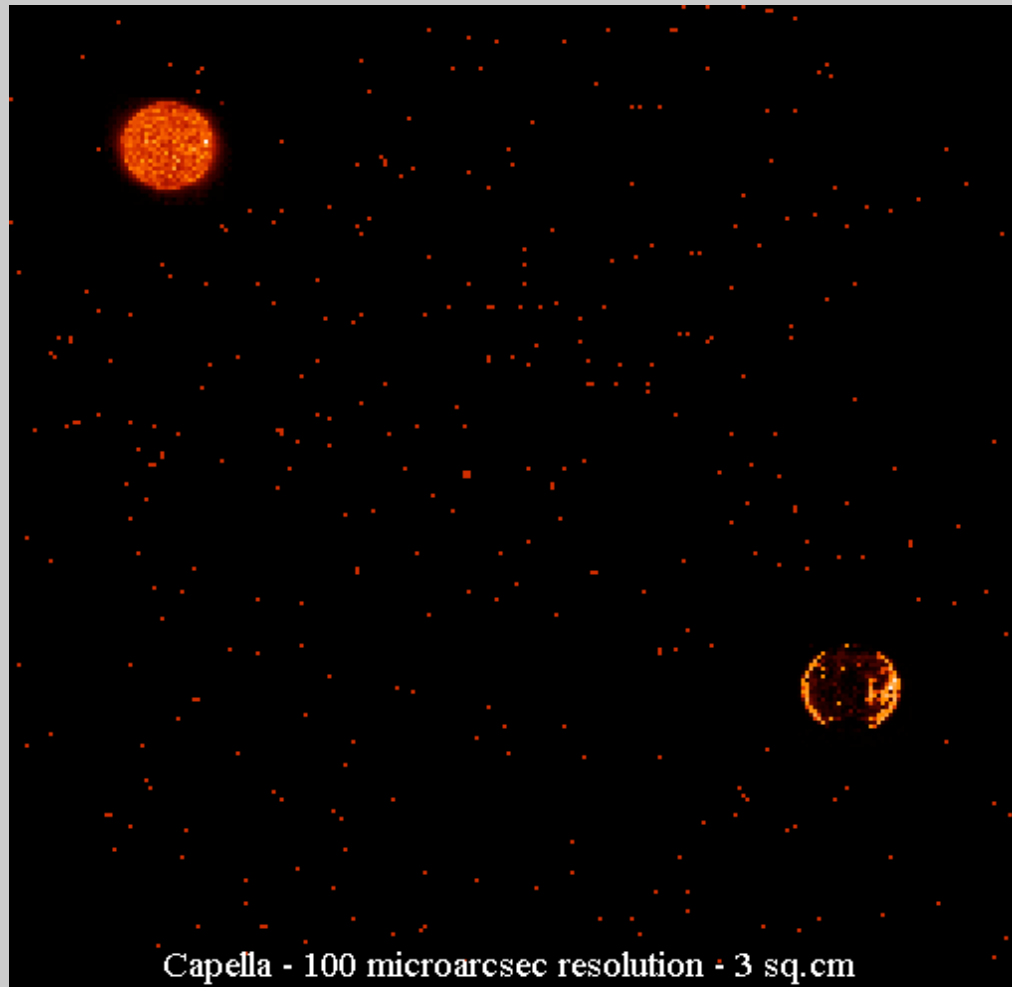
## Science Objectives for the Black Hole Imager (3)



**Map the release of energy in black hole accretion disks –  
Image x-rays at  $0.1\mu\text{as}$**

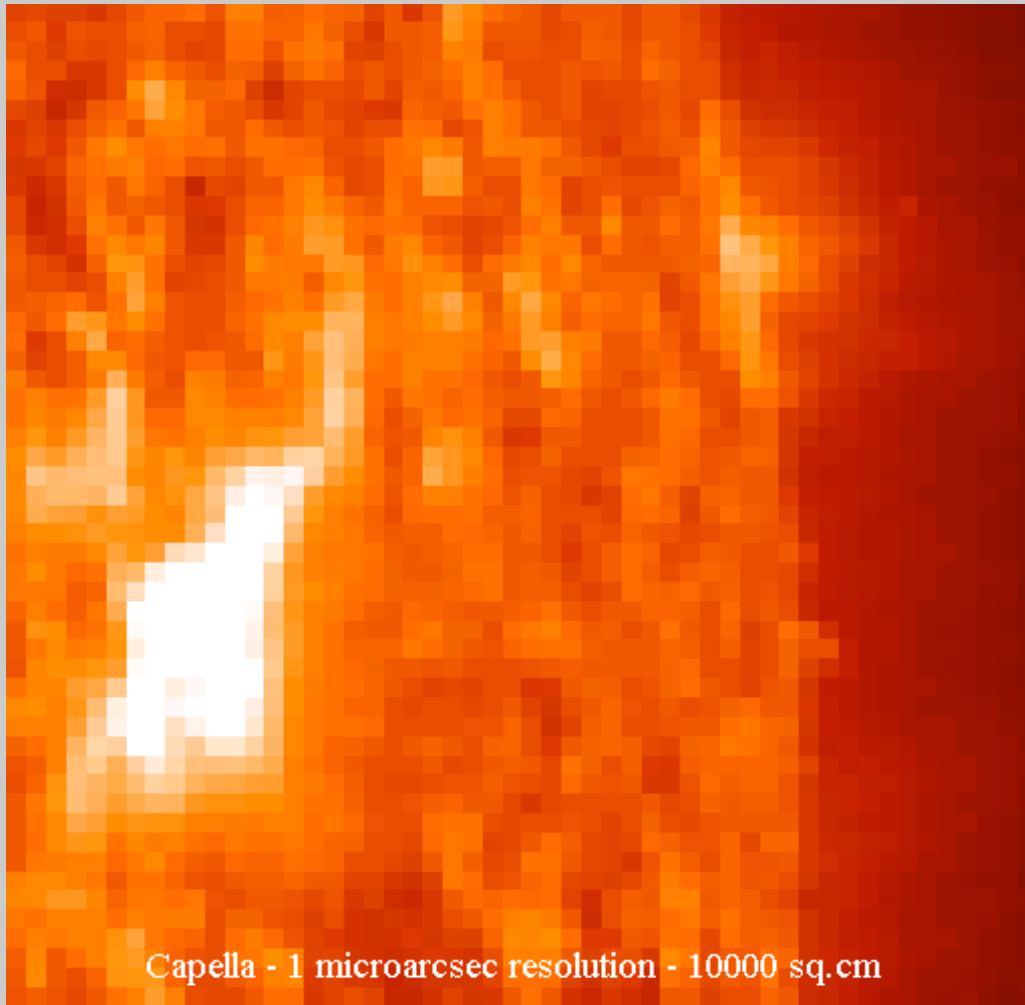
Courtesy of Phil Armitage, U. Colorado and C. Reynolds, U. Maryland

# Capella 100 $\mu$ as



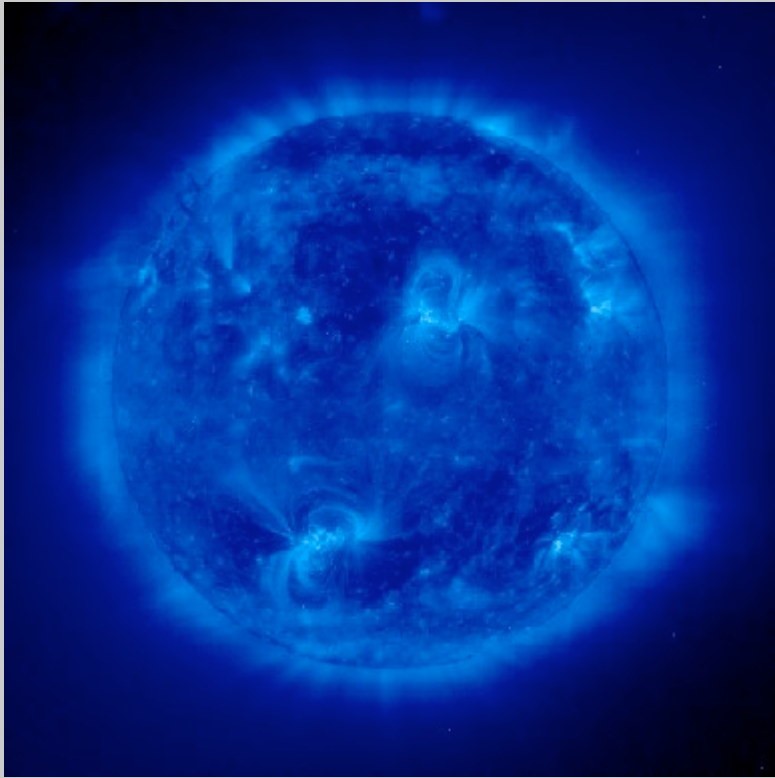
Capella - 100 microarcsec resolution - 3 sq.cm

# Capella 0.000001''



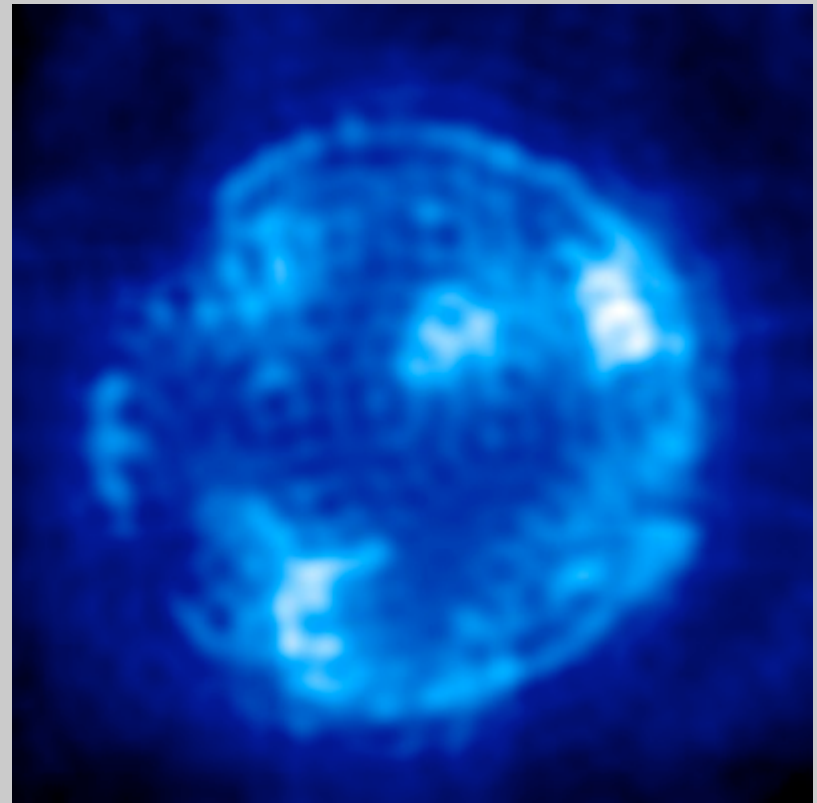
Capella - 1 microarcsec resolution - 10000 sq.cm

# Stars

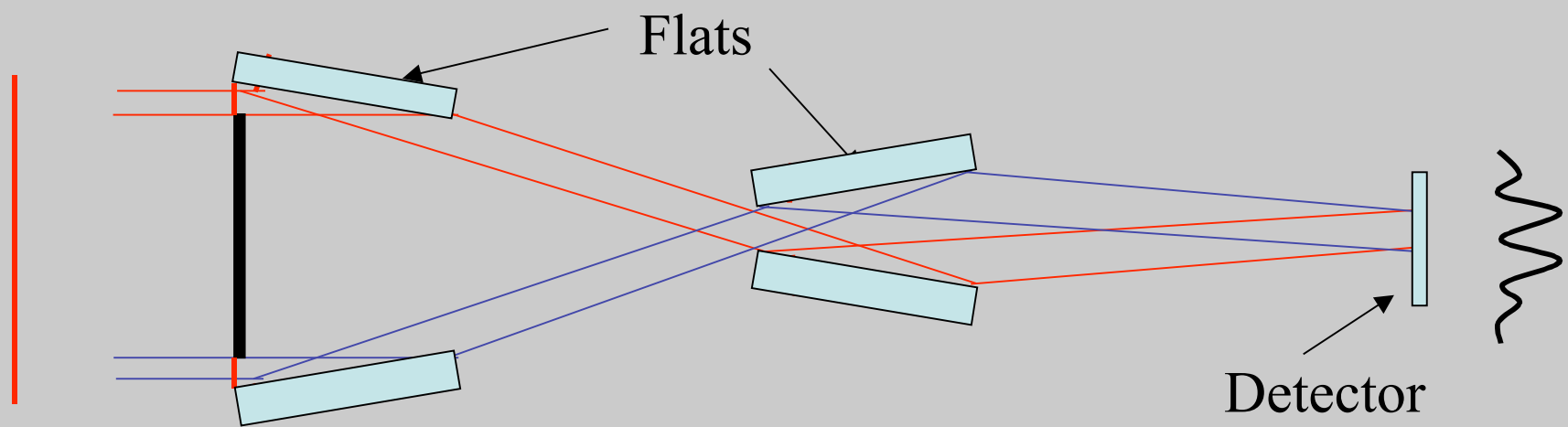


Sun with SOHO

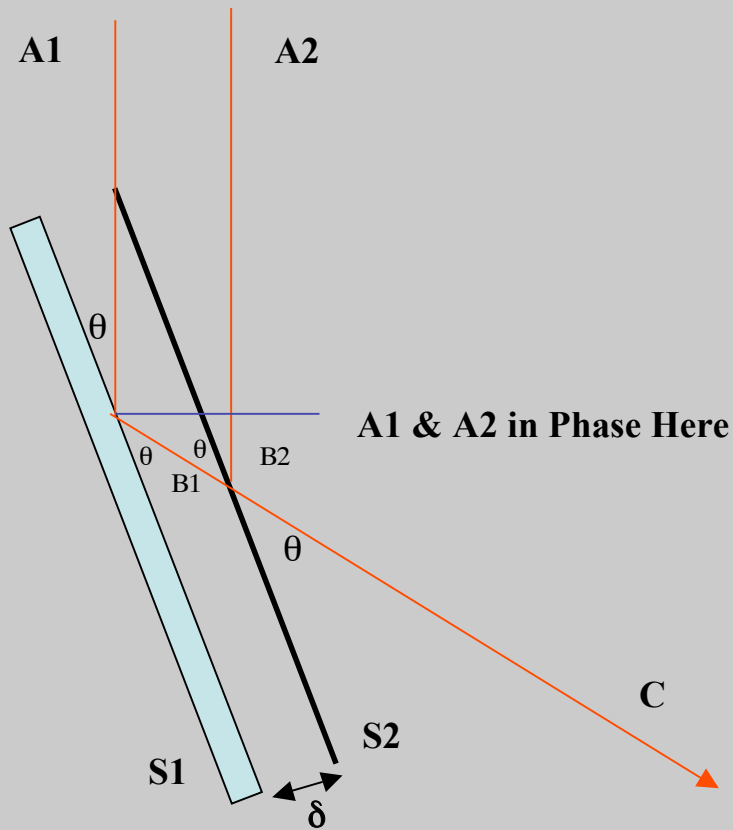
Simulation with Interferometer



# A Simple X-ray Interferometer



## Pathlength Tolerance Analysis at Grazing Incidence



$$B1 = \frac{\delta}{\sin \theta}$$

$$B2 = B1 \cos(2\theta)$$

$$OPD = B1 - B2 = \frac{\delta [1 - \cos(2\theta)]}{\sin \theta} = 2\delta \sin \theta$$

If OPD to be  $< \lambda/10$  then  $\delta < \frac{\lambda}{20 \sin \theta}$

$$d(\text{Baseline}) < \frac{\lambda}{20 \sin \theta \cos \theta}$$

$$d(\text{focal}) < \frac{\lambda}{20 \sin^2 \theta}$$

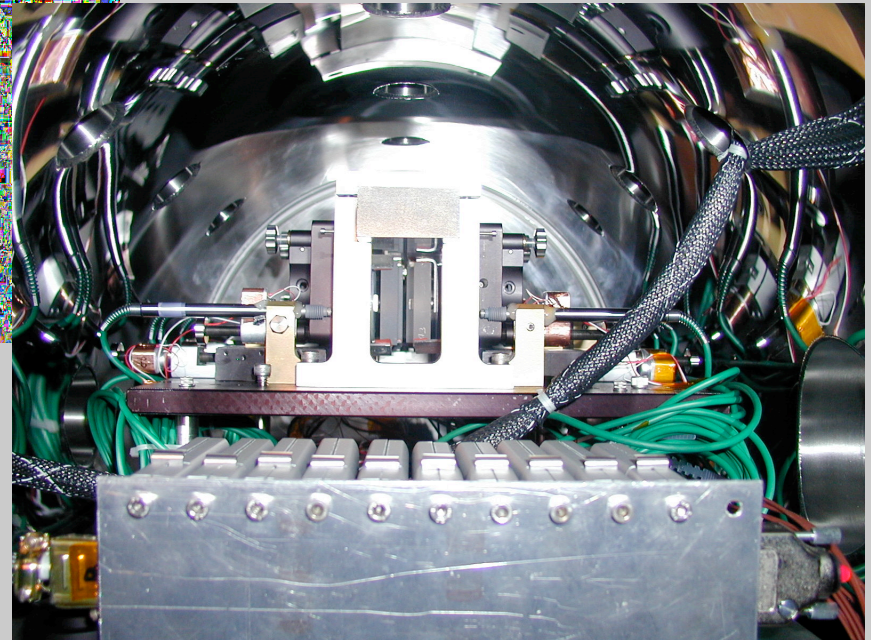


# GSFC X-ray Interferometer



- 80 m long X-ray beam line
- 25 m source to optics
- 50 m focal length
- $\sim 1$  mm baseline
  - (0.25 arcsec at 1 keV)

- Fringe Spacings of 75 to 250 microns  $\rightarrow$  simple vibration suppression at 3 stations



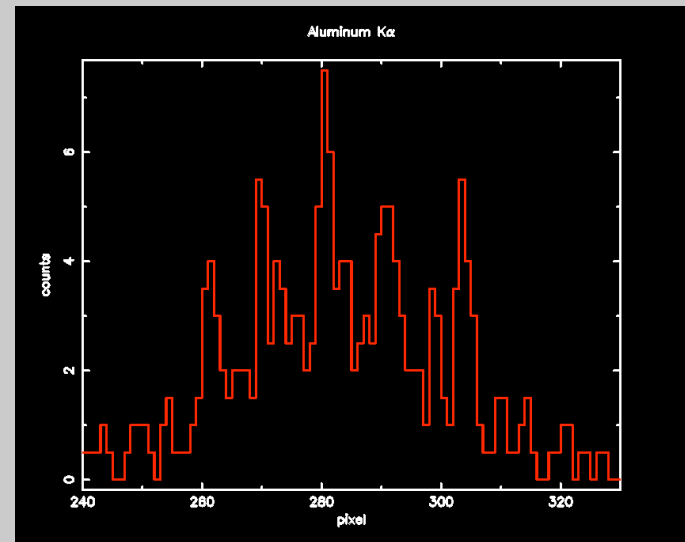


# GSFC X-ray Interferometer Results

- Detected fringes @ 0.525 keV (23 Å) and 1.49 keV (8.35 Å) with a 650 micron baseline (~0.1" at 1.49 keV)
- There are several significant implications of this years work:
  - We have demonstrated interferometry over a factor of 3 of wavelength within the X-ray band.
  - Our measurement at 8.35 Å is the shortest wavelength light to have produced fringes in a broadbandpass interferometer.
  - We have successfully proven a core MAXIM concept

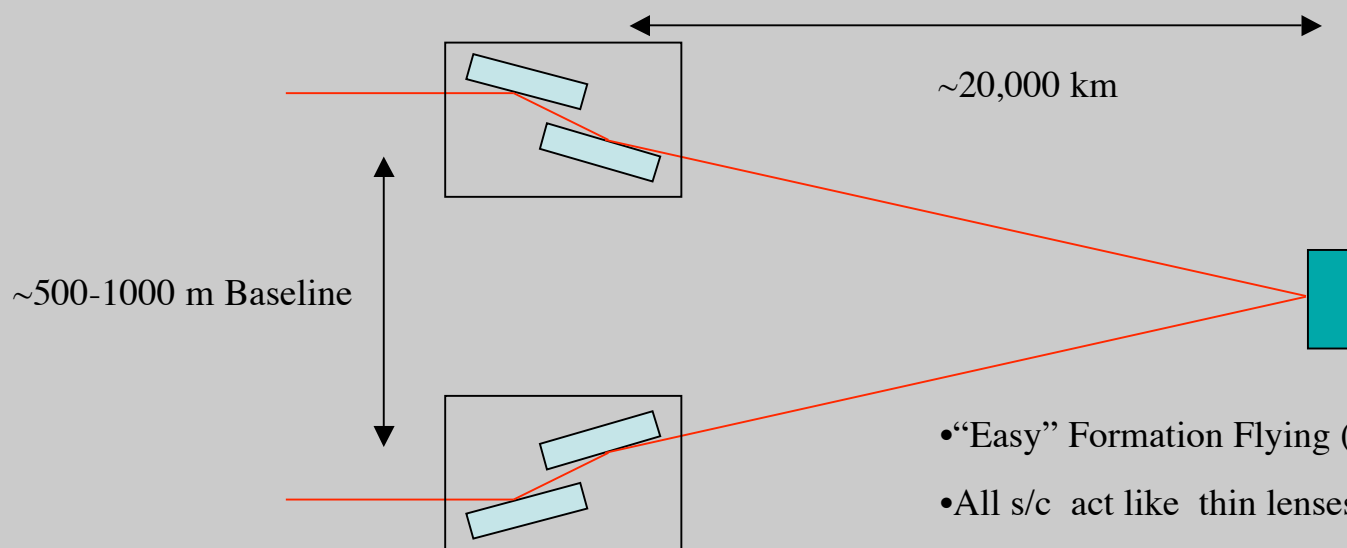
Fringes at 8.35 Å

25 November 2002



# Improved MAXIM Implementation

Group and package Primary and Secondary Mirrors as “Periscope” Pairs

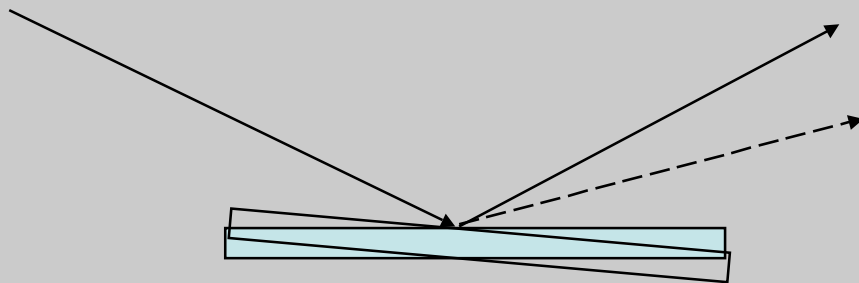


- “Easy” Formation Flying (microns)
- All s/c act like thin lenses- Higher Robustness
- Possibility to introduce phase control within one space craft- an x-ray delay line- More Flexibility
- Offers more optimal UV-Plane coverage- Less dependence on Detector Energy Resolution
- Each Module, self contained- Lower Risk.

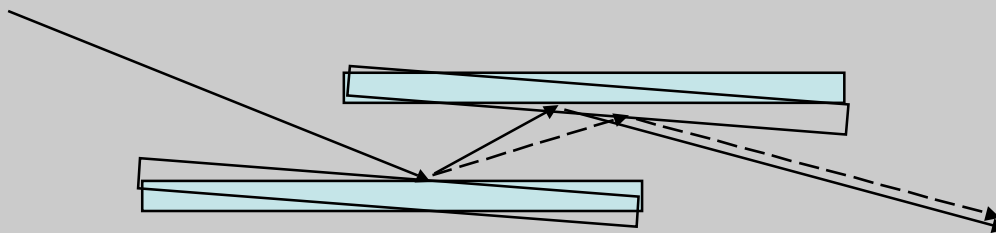
**A scalable MAXIM concept.**

# Periscope Requirements

- Even Number of Reflections

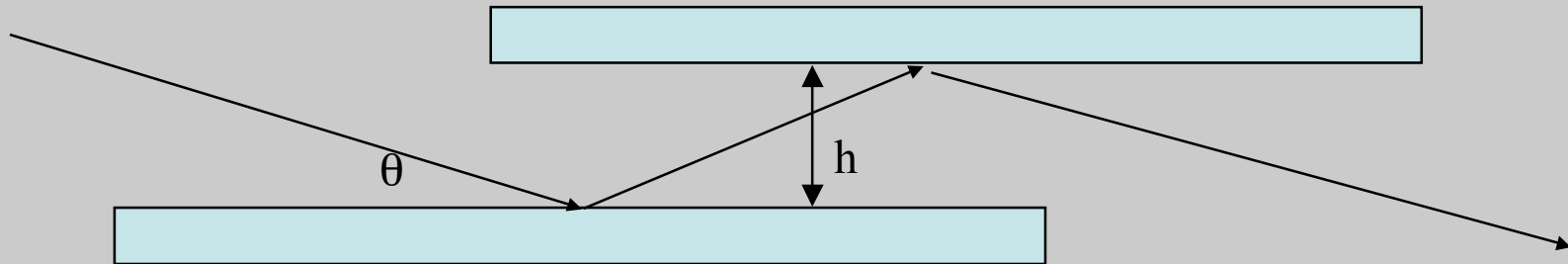


With odd number of reflections, beam direction shifts with mirror tilt



With even number, the mirrors compensate and beam travels in same direction.

# Phase Shift



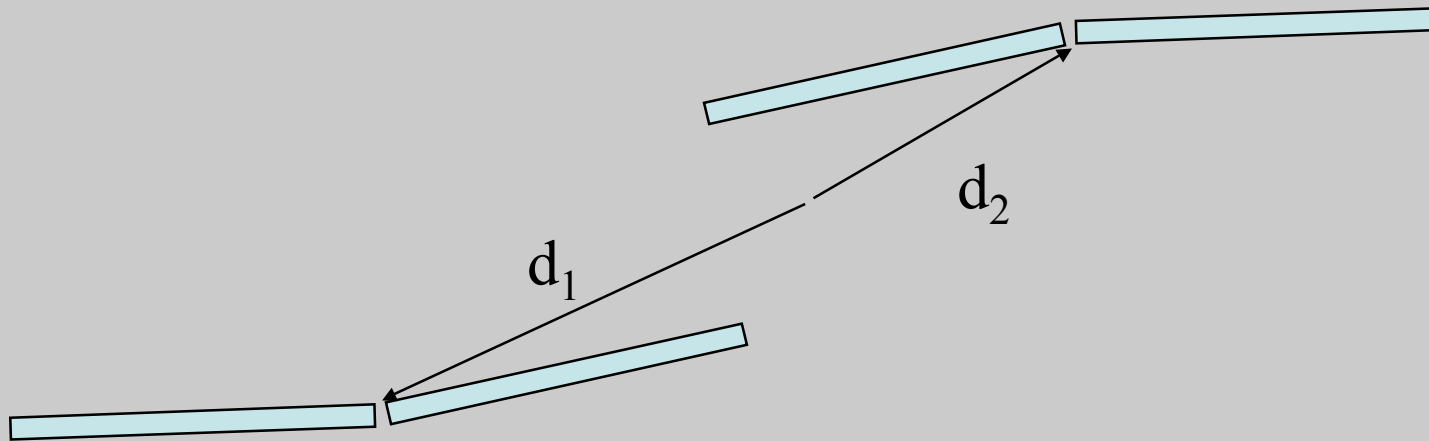
$$\text{Path Delay} = h \sin \theta$$

so  $h \delta \theta < \lambda / 10$  for phase stability

if  $h \sim 1 \text{ cm}$  then  $\delta \theta < 10^{-8}$  (2 milli-arcsec)

*This can be done, but it's not easy.*

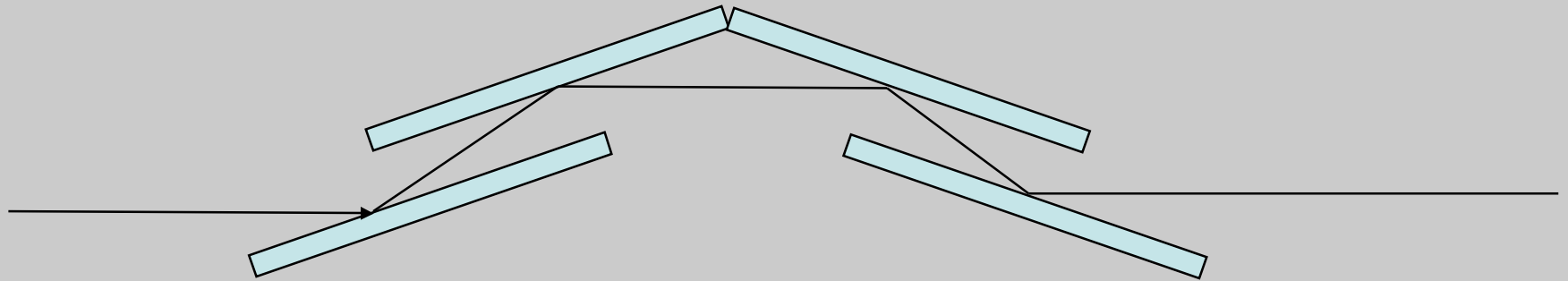
# Phase Delay



$$P = d_1(\cos \beta - \cos \beta \sec(2\theta_2 - 2\theta_1) - \sin \beta \cot \theta_2 + \sin \beta \sec(2\theta_2 - 2\theta_1)(\cot \theta_1 - \cos 2\theta_1(\cot \theta_1 - \cot \theta_2)))$$

$$+ d_2(\cos \beta_2 - \cos \beta_2 \sec(2\theta_4 - 2\theta_3) - \sin \beta_2 \cot \theta_4 + \sin \beta_2 \sec(2\theta_4 - 2\theta_3)(\cot \theta_3 - \cos 2\theta_3(\cot \theta_3 - \cot \theta_4)))$$

# There are Solutions



This solution can be direction and phase invariant

*Dennis Gallagher has verified this by raytrace!*

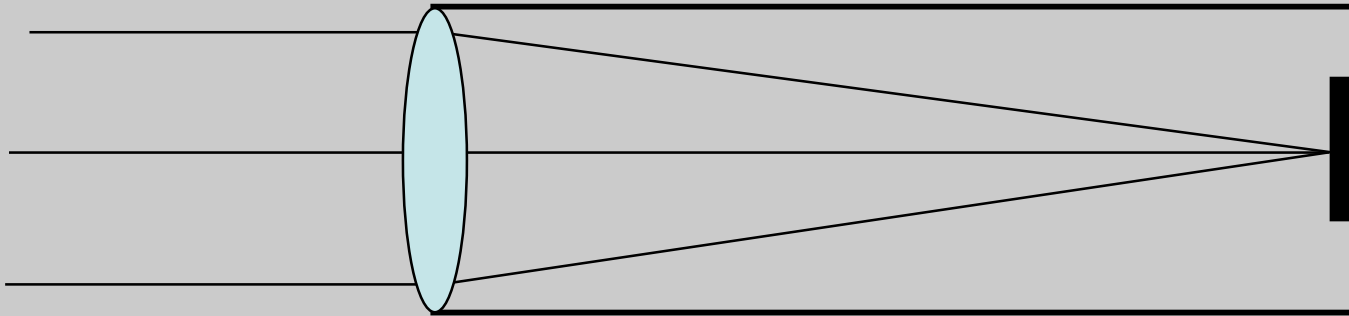
*Pointing can wander arcseconds, even arcminutes, and beam holds fixed!*

# Array Pointing

- 4 mirror periscopes solve problem of mirror stability
- But what about array pointing?
- Doesn't the array have to be stable to  $1\mu\text{as}$  if we are to image to  $1\mu\text{as}$ ?

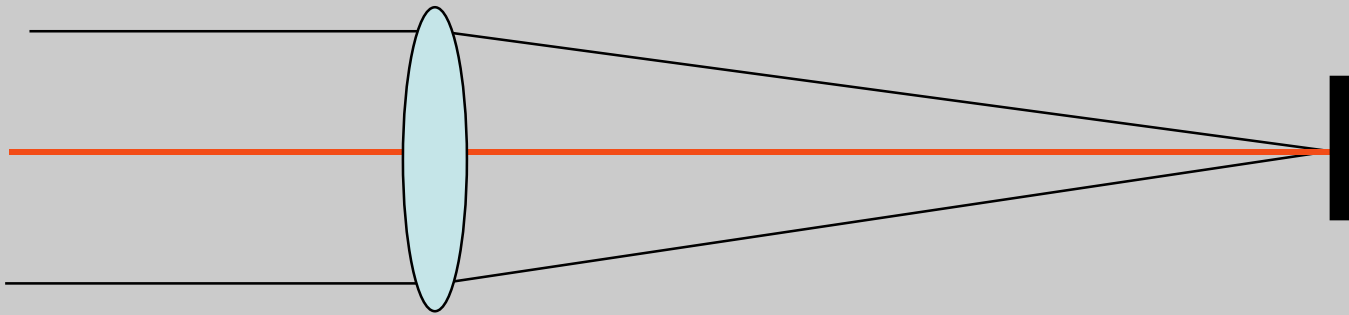


# Thin Lens Behavior



As a thin lens wobbles, the image in space does not move  
Position on the detector changes only because the detector moves

# Formation Flying



If detector is on a separate craft, then a wobble in the lens has no effect on the image.

But motion of detector relative to Line of Sight (red) does!

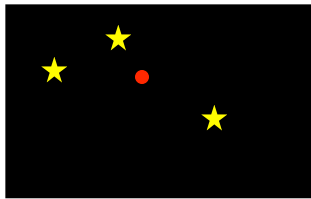
Much easier than stabilizing array.  
Still the toughest nut for full Maxim.  
Variety of solutions under development.

# Technical Components: Line-of-Sight

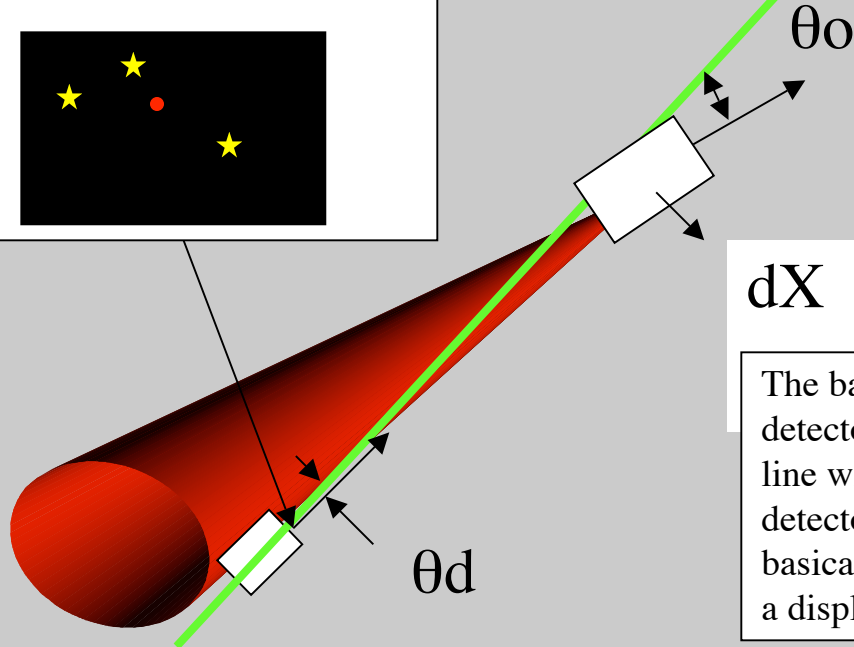
- The individual components need an ACS system good to only arcseconds (they are thin lenses)
- We only ask for relative stability of the LOS- not absolute astrometry
- This is the largest technical hurdle for MAXIM- particularly as the formation flying tolerance has been increased to microns

# Using a “Super Startracker” to align two spacecraft to a target.

In the simplest concept, a Super Star Tracker Sees both Reference stars and a beacon on the other space craft. It should be able to track relative drift between the reference and the beacon to 30 microarcseconds- in the case of MAXIM Pathfinder.



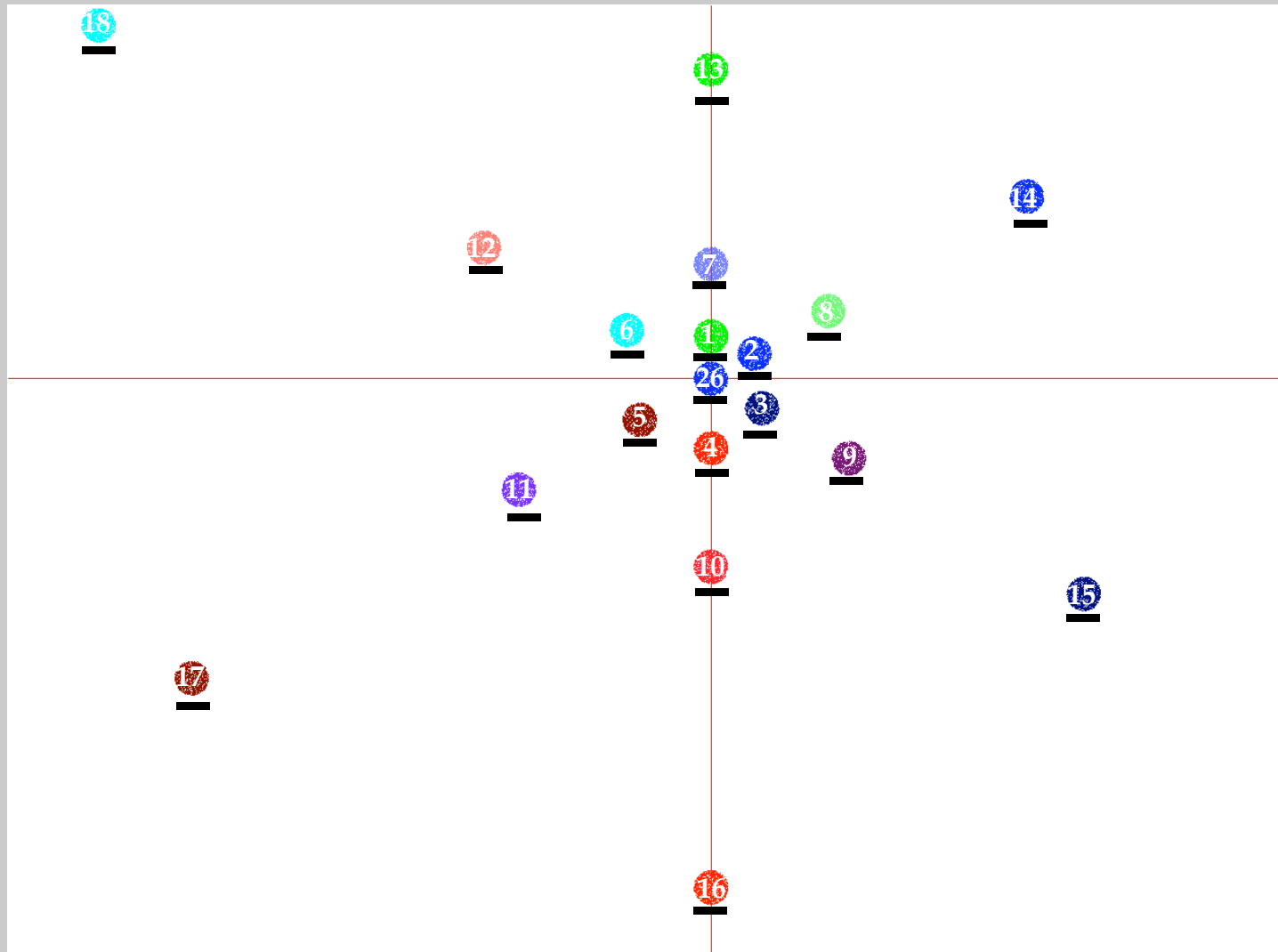
For a number of reasons (proper motion, aberration of light, faintness of stars,...) an inertial reference may be more appropriate than guiding on stars. The inertial reference has to be stable at a fraction of the angular resolution for hours to a day. This would require an extremely stable gyroscope (eg GP-B, superfluid gyroscopes, atomic interferometer gyroscopes).



dX

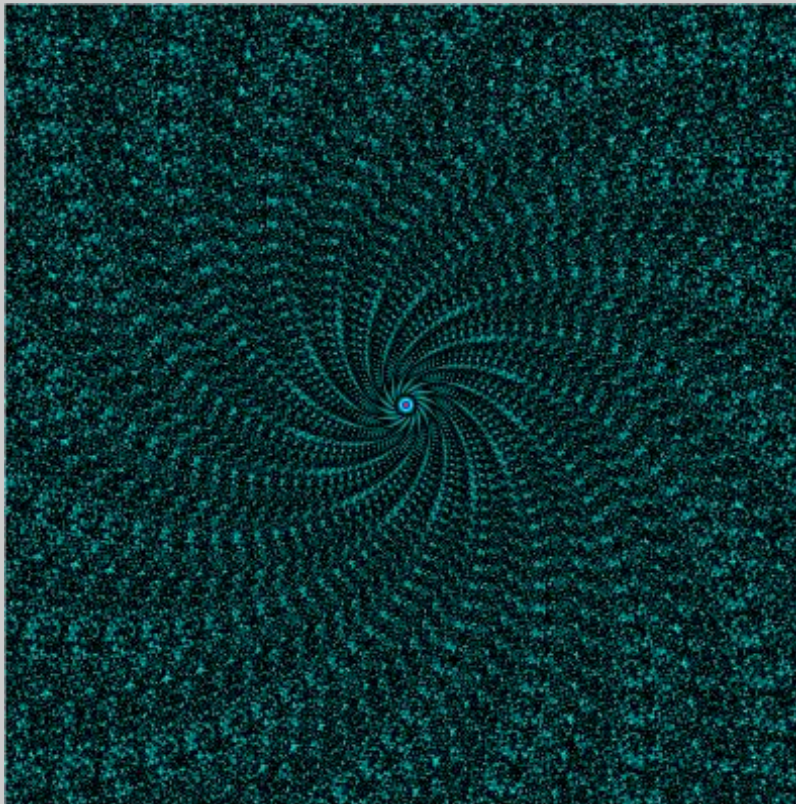
The basic procedure here, is to align three points (the detector, the optics, and the target) so they form a straight line with “kinks” less than the angular resolution. The detector and the optics behave as thin lenses- and we are basically insensitive to their rotations. We are sensitive to a displacement from the Line-of-Sight (eg dX).

# Aperture Locations (central area)



# Beam from One Craft

(1000cm<sup>2</sup> effective, 60μas resolution)



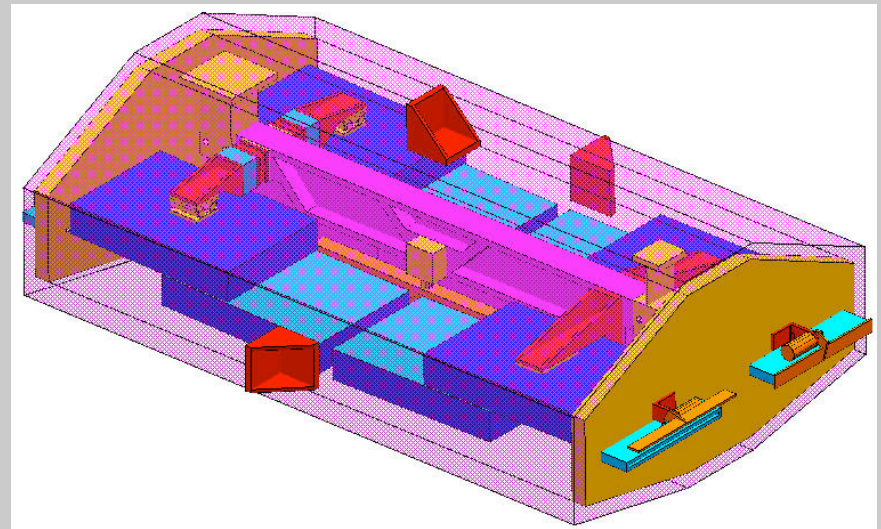
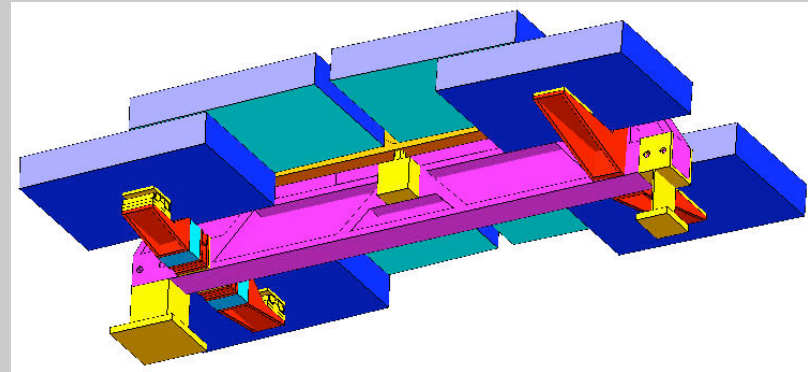
**Amplitude**



**Intensity**

# Evolution of the Periscope Design

- A 2 mirror periscope has tight (mas) pointing requirements
- We get around this by adding 2 more mirrors- now the pointing requirement is 10 arcseconds
- Reduced effective area, but we still enjoy advantages
  - ~10 micron formation flying
  - Phasing to allow better UV plane coverage
  - Lower risk
  - Lower Cost (~<\$60M to make 1000 cm<sup>2</sup> of area)

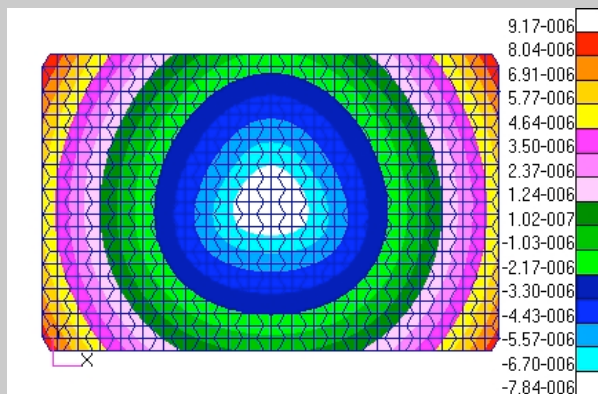




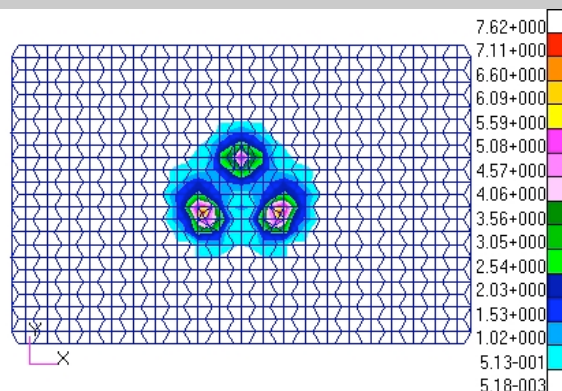
# Mirror Analysis Summary

Analysis	Goal/Req.	Result	Comments
1°c Bulk Temp Load	min surface deformation	PtoV=6.2nm, RMS=1.2nm	
1°c X Gradient	min surface deformation	PtoV=3.2nm, RMS=0.6nm	Gradient across mirror surface
1°c Y Gradient	min surface deformation	PtoV=3.1nm, RMS=0.6nm	Gradient across mirror surface
1°c Z Gradient	min surface deformation	PtoV=17.0nm, RMS=3.8nm	Gradient through mirror thickness
Fixed Base Dynamics	FF > 100 Hz	FF=278 Hz	Mirror on flexures, but not entire mount
20g Quasi Static Load	Mount Stress < Yield	35 MPa maximum	20g Y Loading
20g Quasi Static Load	Low Mirror Stress	7.6MPa maximum	20g Y Loading

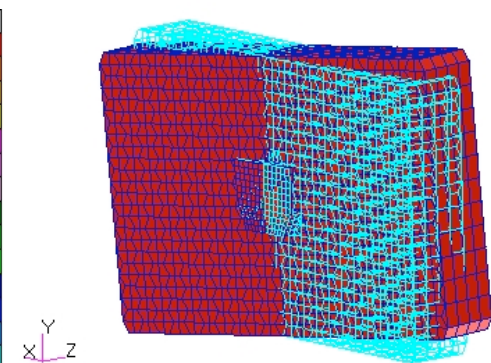
1cZ Mirror Deformations (mm)



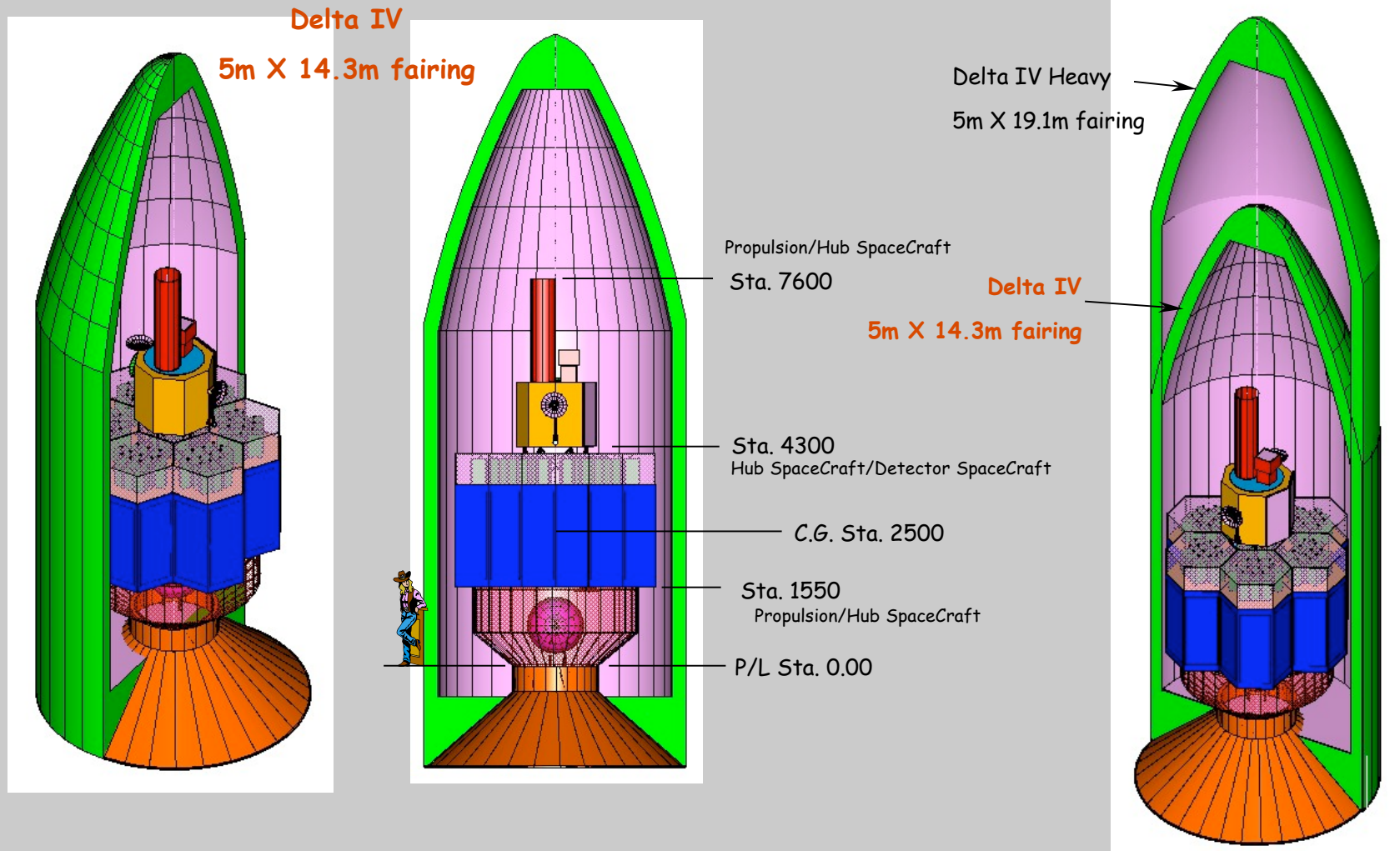
20gY Mirror Back Stresses (MPa)



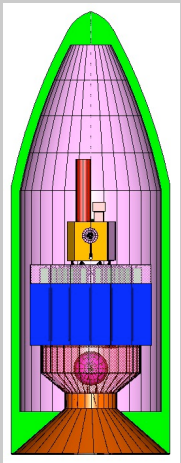
Mirror First Mode = 278 Hz



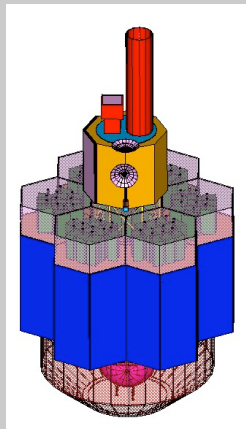
# Pathfinder Configuration



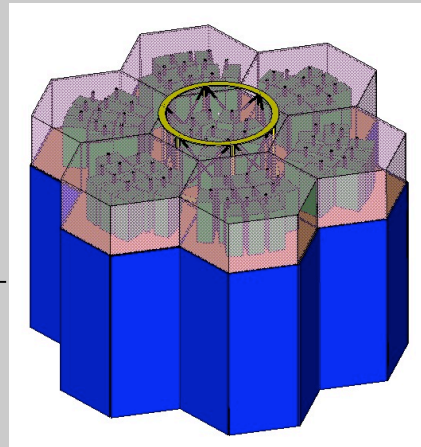
# Mission Sequence



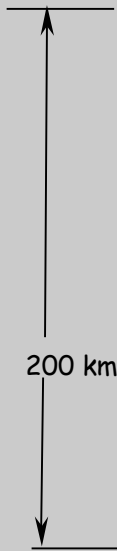
Launch



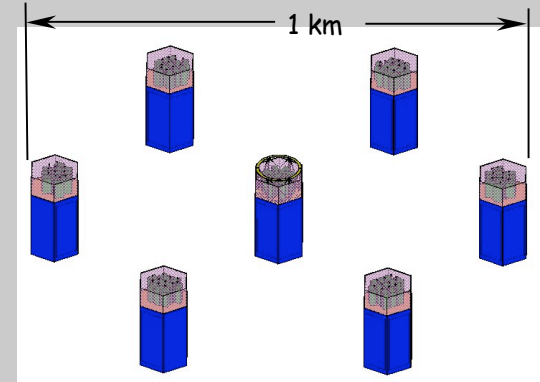
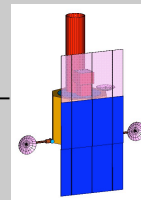
Transfer Stage



Science Phase #1  
Low Resolution ( $100 \mu\text{as}$ )



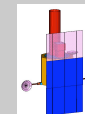
200 km



Science Phase #2  
High Resolution  
( $100 \text{ nas}$ )



20,000 km



# Key Technical Challenges

- Optics State of the Art (but not beyond)
- “Periscope” implementation loosens formation flying tolerance from nm to  $\mu\text{m}$ .
- Line-of-sight alignment of multiple spacecraft with our target is the most serious challenge- and MAXIM is not alone with this.
- Optimal image formation through pupil densification is being studied

*IMDC has verified that this mission is achievable  
with  
today's technology.*

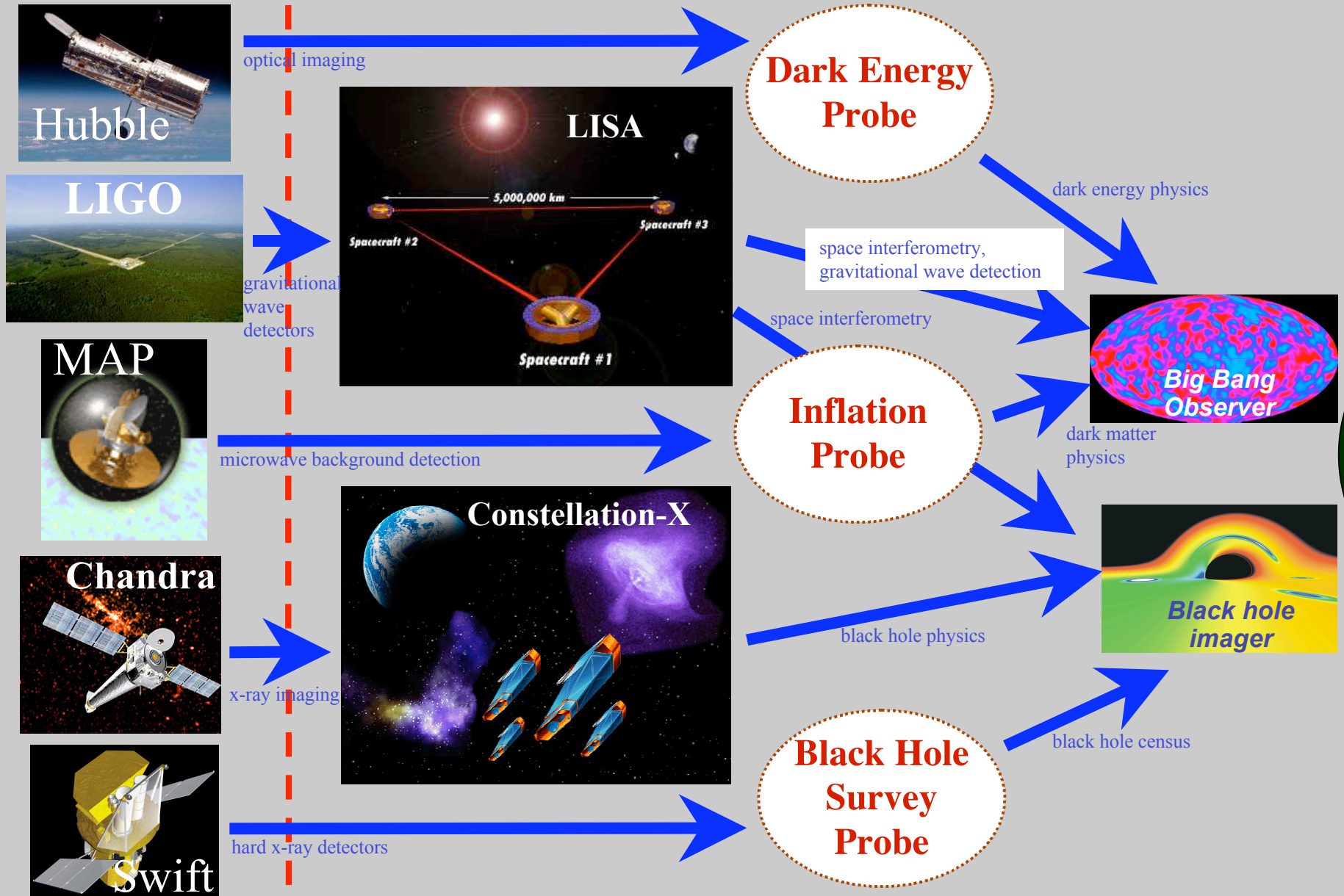
*Decadal review recommended technology development money  
that so far has not been forthcoming*

*Launch is in the indefinite future*

*But*

*once we know its possible then we are going to have to do it*

# The Beyond Einstein Program



Science and Technology Precursors